

## CRAMER'S RULE IN INTERVAL MIN-PLUS ALGEBRA

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### ABSTRACT

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A min-plus algebra is a set  $\mathbb{R}_{\varepsilon'} = \mathbb{R} \cup \{-\infty\}$ , where  $\mathbb{R}$  is the set of all real numbers, equipped with the minimum ( $\oplus'$ ) and addition ( $\otimes$ ) operations. The system of linear equations  $A \otimes x = b$  in min-plus algebra can be solved using Cramer's rule. Interval min-plus algebra is an extension of min-plus algebra, with the elements in it being closed intervals. The set is denoted by  $I(\mathbb{R})_{\varepsilon'}$  equipped with two binary operations, namely minimum ( $\oplus'$ ) and addition ( $\otimes$ ). The matrix with notation  $I(\mathbb{R})_{\varepsilon'}^{m \times n}$  is a matrix over interval min-plus algebra with size  $m \times n$ . Since the structure of min-plus algebra and interval min-plus algebra are analogous, the system of linear equations  $A \otimes x = b$  in interval min-plus algebra can be solved using Cramer's rule. Based on the research results, the sufficient conditions of Cramer's rule in interval min-plus algebra are  $\text{sign}(A_i) = \text{sign}(\underline{A})$ ,  $\text{sign}(\overline{A}_i) = \text{sign}(\overline{A})$  for  $1 \leq i \leq n$ , and  $\text{dom}(A) = [\text{dom}(\underline{A}), \text{dom}(\overline{A})] < [\varepsilon', \varepsilon']$ . The Cramer rule is  $x_i \otimes \text{dom}(A) = \text{dom}(A_i)$ .



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## 1. INTRODUCTION

In algebra, there are various structures, and one of them is conventional algebra. Conventional algebra is the set of all real numbers equipped with addition (+) and multiplication ( $\times$ ) operations [1]. In conventional algebra, a system of linear equations is expressed as  $Ax = b$ . As long as  $\det(A) \neq 0$ , Cramer's rule can be used to solve the system of linear equations  $Ax = b$  [2][3].

There is another structure, namely max-plus algebra [4]. In max-plus algebra, the maximum operation does not have an inverse so the determinant in max-plus algebra is not defined similarly to conventional algebra. There are two methods for representing determinants in max-plus algebra, permanent and dominant. [5][6]. The system of linear equations  $A \otimes x = b$  in max-plus algebra can be solved using Cramer's rule with dominant values [7][8][9]. Then, interval max-plus algebra is created by extending max-plus algebra [10][11][12]. The system of linear equations  $A \overline{\otimes} x = b$  in interval max-plus algebra can also be solved using Cramer's rule with dominant value [13][14].

A min-plus algebra is the set  $\mathbb{R}_{\varepsilon'} = \mathbb{R} \cup \{-\infty\}$ , where  $\mathbb{R}$  is the set of all real numbers, equipped with the minimum ( $\oplus'$ ) and addition ( $\otimes$ ) operations. Therefore, the operation  $a \oplus' b = \min(a, b)$  and  $a \otimes b = a + b$  applies. Min-plus algebra is a semiring denoted by  $\mathbb{R}_{min} = (\mathbb{R}_{\varepsilon'}, \oplus', \otimes)$  and has a neutral element  $\varepsilon' = +\infty$  for the minimum operation and a neutral element  $e = 0$  for the addition operation [15][16]. Min-plus algebra can be formed into a set of matrices of size  $m \times n$ ,  $m$  and  $n$  are positive integers, with the entries being elements of  $\mathbb{R}_{\varepsilon'}$  and denoted as  $\mathbb{R}_{\varepsilon'}^{m \times n}$  [17][18][19]. The determinant in min-plus algebra is represented the same as in max-plus algebra, which is permanent and dominant [17]. The system of linear equations  $A \otimes x = b$  in min-plus algebra always has the smallest sub-solution. Cramer's rule in min-plus algebra is  $x_i \otimes \text{dom}(A) = \text{dom}(a_1, \dots, a_{i-1}, b, a_{i+1}, \dots, a_n)$ ,  $i = 1, 2, \dots, n$  with  $a_j$  is the entry in the  $j$ -th column of the matrix  $A$ . The solution of the system of linear equations  $A \otimes x = b$  does not necessarily exist in min-plus algebra, and if it does, it is not always singular, much as in conventional algebra. As a result, an additional condition is needed so that the system of linear equations can be solved using Cramer's rule, namely  $\text{sign}(a_1, \dots, a_{i-1}, b, a_{i+1}, \dots, a_n) = \text{sign}(A)$  for  $i = 1, 2, \dots, n$  with  $a_j$  is the entry in the  $j$ -th column of the matrix  $A$  [20].

Interval min-plus algebra is an extension of min-plus algebra, with elements in it being closed intervals. The set is denoted by  $I(\mathbb{R})_{\varepsilon'}$ , equipped with two binary operations, namely minimum ( $\overline{\oplus}'$ ) and addition ( $\overline{\otimes}$ ). The structure of interval min-plus algebra can be written as  $I(\mathbb{R})_{min} = (I(\mathbb{R})_{\varepsilon'}, \overline{\oplus}', \overline{\otimes})$  [21]. The matrix with the notation  $I(\mathbb{R})_{\varepsilon'}^{m \times n}$  is a matrix over interval min-plus algebra with size  $m \times n$ . If  $m = n$ , a set of square matrices is obtained, namely  $I(\mathbb{R})_{\varepsilon'}^{n \times n}$  [22][23]. Similar to min-plus algebra, the determinant in an interval min-plus algebra is defined with two approaches,  $\text{perm}(A) = [\text{perm}(\underline{A}), \text{perm}(\overline{A})]$  with  $\text{perm}(\underline{A}) = \oplus'_{\sigma \in P_n} \otimes_{i=1}^n (\underline{a}_{i\sigma(i)})$  and  $\text{perm}(\overline{A}) = \oplus'_{\sigma \in P_n} \otimes_{i=1}^n (\overline{a}_{i\sigma(i)})$  and dominant i.e.  $\text{dom}(A) = [\min(\text{dom}(\underline{A}), \text{dom}(\overline{A})), \text{dom}(\overline{A})]$  with  $\text{dom}(\underline{A}) = \begin{cases} \text{lowest exponent in } \det(z^{\underline{A}}), & \text{if } \det(z^{\underline{A}}) \neq 0 \\ \varepsilon', & \text{if } \det(z^{\underline{A}}) = 0 \end{cases}$  and  $\text{dom}(\overline{A}) = \begin{cases} \text{lowest exponent in } \det(z^{\overline{A}}), & \text{if } \det(z^{\overline{A}}) \neq 0 \\ \varepsilon', & \text{if } \det(z^{\overline{A}}) = 0 \end{cases}$  [24]. In this article, we will discuss the

sufficient conditions for a system of linear equations  $A \overline{\otimes} x = b$  in interval min-plus algebra to be solved using Cramer's rule and its solution.

## 2. RESEARCH METHODS

The research method used in writing this article is a literature study by using references to books, articles from [20][24] or writings on interval min-plus algebra, matrices over interval min-plus algebra, and systems of linear equations over interval min-plus algebra. In addition, it also uses references that discuss min-plus algebra and Cramer's rule in min-plus algebra.

In this study, three steps were taken which are described as follows.

1. Determine Cramer's rule in interval min-plus algebra using matrix dominants based on analogies corresponding to min-plus algebra.
2. Determine the definition of *sign* matrix over interval min-plus algebra.
3. Determine the sufficient condition that the system of linear equations  $A \overline{\otimes} x = b$  in interval min-plus algebra can be solved using Cramer's rule.

### 3. RESULTS AND DISCUSSION

Suppose  $A \approx [\underline{A}, \overline{A}] \in I(\mathbb{R})_{\varepsilon'}^{n \times n}$ ,  $x \approx [\underline{x}, \overline{x}] \in I(\mathbb{R})_{\varepsilon'}^{n \times 1}$ , and  $b \approx [\underline{b}, \overline{b}] \in I(\mathbb{R})_{\varepsilon'}^{n \times 1}$ , the system of linear equations  $A \overline{\otimes} x = b$  in interval min-plus algebra always has a smallest sub-solution. The smallest sub-solution is not always the solution of a system of linear equations.

Determinants in interval min-plus algebra are represented with two approaches, namely permanent and dominant. By the same analogy with min-plus algebra, the system of linear equations  $A \overline{\otimes} x = b$  with  $A \approx [\underline{A}, \overline{A}] \in I(\mathbb{R})_{\varepsilon'}^{n \times n}$ ,  $x \approx [\underline{x}, \overline{x}] \in I(\mathbb{R})_{\varepsilon'}^{n \times 1}$ , and  $b \approx [\underline{b}, \overline{b}] \in I(\mathbb{R})_{\varepsilon'}^{n \times 1}$  in interval min-plus algebra always has the smallest subsolution. The smallest sub-solution is not always the solution of a system of linear equations. The solution of a system of linear equations in interval min-plus algebra is presented in **Lemma 1**.

**Lemma 1.** Suppose  $A \approx [\underline{A}, \overline{A}]$ ,  $x \approx [\underline{x}, \overline{x}]$ , and  $b \approx [\underline{b}, \overline{b}]$ . If the linear equations  $\underline{A} \otimes \underline{x} = \underline{b}$  and  $\overline{A} \otimes \overline{x} = \overline{b}$  each has a single solution  $\underline{\check{x}} = -(\underline{A}^T \otimes (-\underline{b}))$  and  $\overline{\check{x}} = -(\overline{A}^T \otimes (-\overline{b}))$  with  $\underline{\check{x}} \leq \overline{\check{x}}$  then the system of linear equations  $A \overline{\otimes} x = b$  has a single solution  $x \approx [\underline{\check{x}}, \overline{\check{x}}]$ .

**Proof.** Suppose  $A \approx [\underline{A}, \overline{A}]$ ,  $x \approx [\underline{x}, \overline{x}]$ , and  $b \approx [\underline{b}, \overline{b}]$ . According to the matrix operations in the min-plus algebra of intervals  $A \overline{\otimes} x \approx [\underline{A}, \overline{A}] \overline{\otimes} [\underline{x}, \overline{x}] = [\underline{A} \otimes \underline{x}, \overline{A} \otimes \overline{x}]$ . This means that  $\underline{A} \otimes \underline{x} = \underline{b}$  and  $\overline{A} \otimes \overline{x} = \overline{b}$ . Since the linear equation systems  $\underline{A} \otimes \underline{x} = \underline{b}$  and  $\overline{A} \otimes \overline{x} = \overline{b}$  each has a single solution  $\underline{\check{x}} = -(\underline{A}^T \otimes (-\underline{b}))$  and  $\overline{\check{x}} = -(\overline{A}^T \otimes (-\overline{b}))$  with  $\underline{\check{x}} \leq \overline{\check{x}}$  then the system of linear equations  $A \overline{\otimes} x = b$  has a single solution  $x \approx [\underline{\check{x}}, \overline{\check{x}}]$ .

Cramer's rule in interval min-plus algebra is written as,

$$x_i \overline{\otimes} \text{dom}(A) = \text{dom}(A_i), i = 1, 2, \dots, n, \tag{1}$$

with  $A_i = a_1, \dots, a_{i-1}, b, a_{i+1}, \dots, a_n$  and  $A_i \approx [\underline{A}_i, \overline{A}_i]$  then  $\underline{A}_i = \underline{a}_1, \dots, \underline{a}_{i-1}, \underline{b}, \underline{a}_{i+1}, \dots, \underline{a}_n$  and  $\overline{A}_i = \overline{a}_1, \dots, \overline{a}_{i-1}, \overline{b}, \overline{a}_{i+1}, \dots, \overline{a}_n$ .

Furthermore, if  $\text{dom}(A) \approx [\text{dom}(\underline{A}), \text{dom}(\overline{A})]$  and  $\text{dom}(A_i) \approx [\text{dom}(\underline{A}_i), \text{dom}(\overline{A}_i)]$  then it means  $\underline{x}_i \leq \overline{x}_i$ . Hence it holds

$$x_i \overline{\otimes} \text{dom}(A) = \text{dom}(A_i) \Leftrightarrow \underline{x}_i \otimes \text{dom}(\underline{A}) = \text{dom}(\underline{A}_i) \text{ and } \overline{x}_i \otimes \text{dom}(\overline{A}) = \text{dom}(\overline{A}_i) \tag{2}$$

Analogous to Cramer's rule in min-plus algebra,  $\text{dom}(A) \approx [\text{dom}(\underline{A}), \text{dom}(\overline{A})] < [\varepsilon', \varepsilon']$  is not enough to show that the system of linear equations has a solution. There is an additional condition for the system of linear equations  $A \overline{\otimes} x = b$  to have a solution, namely

$$\text{sign}(\underline{A}_i) = \text{sign}(\underline{A}) \text{ and } \text{sign}(\overline{A}_i) = \text{sign}(\overline{A}), \tag{3}$$

for  $1 \leq i \leq n$ . The following is a description of the notations used to define the *sign* of a matrix.

**Definition 1.** Let  $P_n$  be the set of all permutations of  $\{1, 2, \dots, n\}$  and  $t_1, t_2, \dots, t_L$  are all possible values such that  $\underline{t}_j = \otimes_{j=1}^n (\underline{a}_{j\sigma(j)})$  and  $\overline{t}_j = \otimes_{j=1}^n (\overline{a}_{j\sigma(j)})$  with  $\text{dengan } A = [a_{ij}] \in I(\mathbb{R})_{\varepsilon'}^{n \times n}$ ,  $A \approx [\underline{A}, \overline{A}]$  for all permutations  $\sigma \in P_n$ . Given  $\underline{S}_j$  and  $\overline{S}_j$  suppose that

$$\underline{S}_j = \{ \sigma \in P_n \mid \underline{t}_j = \otimes_{j=1}^n (\underline{a}_{j\sigma(j)}) \},$$

$$\begin{aligned}\underline{S}_{je} &= \{\sigma \in \underline{S}_j \mid \sigma \in P_n^e\}, \\ \underline{S}_{jo} &= \{\sigma \in \underline{S}_j \mid \sigma \in P_n^o\}, \\ \underline{k}_{je} &= |\underline{S}_{je}|, \text{ and } \underline{k}_{jo} = |\underline{S}_{jo}|,\end{aligned}$$

and

$$\begin{aligned}\bar{S}_j &= \{\sigma \in P_n \mid \bar{t}_j = \otimes_{j=1}^n (\bar{a}_{j\sigma(j)})\}, \\ \bar{S}_{je} &= \{\sigma \in \bar{S}_j \mid \sigma \in P_n^e\}, \\ \bar{S}_{jo} &= \{\sigma \in \bar{S}_j \mid \sigma \in P_n^o\}, \\ \bar{k}_{je} &= |\bar{S}_{je}|, \text{ and } \bar{k}_{jo} = |\bar{S}_{jo}|.\end{aligned}$$

With  $P_n^e$  and  $P_n^o$  being the set of all even and odd permutations of  $P_n$ , respectively.

Using **Definition 1**, the following definition of the sign is obtained.

**Definition 2.** Given  $A = [a_{ij}] \in I(\mathbb{R})_{\varepsilon'}^{n \times n}$  with  $A \approx [\underline{A}, \bar{A}]$ . For  $\underline{t}_j = \text{dom}(\underline{A})$ ,  $\bar{t}_j = \text{dom}(\bar{A})$ , and  $1 \leq j \leq L$ ,  $\text{sign}(\underline{A}) = \begin{cases} 1, \text{ if } \underline{k}_{je} - \underline{k}_{jo} > 0 \\ -1, \text{ if } \underline{k}_{je} - \underline{k}_{jo} < 0 \end{cases}$  and  $\text{sign}(\bar{A}) = \begin{cases} 1, \text{ if } \bar{k}_{je} - \bar{k}_{jo} > 0 \\ -1, \text{ if } \bar{k}_{je} - \bar{k}_{jo} < 0 \end{cases}$ . If  $\text{dom}(\underline{A}) = \varepsilon'$  and  $\text{dom}(\bar{A}) = \varepsilon'$  then  $\text{sign}(A) = \varepsilon'$  and  $\text{sign}(\bar{A}) = \varepsilon'$ .

**Example 1.** Given matrix  $A \in I(\mathbb{R})_{\varepsilon'}^{3 \times 3}$

$$A = \begin{pmatrix} [2,3] & [2,5] & [0,2] \\ [3,5] & [-2,-1] & [-1,0] \\ [-1,2] & [2,3] & [1,3] \end{pmatrix}$$

Interval matrix  $A$  can be written as matrix interval  $[\underline{A}, \bar{A}]$  i.e.

$$A \approx [\underline{A}, \bar{A}] = \left[ \begin{pmatrix} 2 & 2 & 0 \\ 3 & -2 & -1 \\ 5 & 2 & 1 \end{pmatrix}, \begin{pmatrix} 3 & 5 & 2 \\ 5 & -1 & 0 \\ 2 & 3 & 3 \end{pmatrix} \right]$$

Matrix  $A$  is a matrix with  $n = 3$  so we get  $3! = 3 \times 2 \times 1 = 6$ . This means there are six permutations of  $\{1, 2, 3\}$  with each result of the permutation of  $\underline{t}_j$  and  $\bar{t}_j$  shown in **Table 1**.

**Table 1. Result of Permutation  $n = 3$  of  $\underline{t}_j$  and  $\bar{t}_j$**

$\sigma_j = 1, 2, 3$	$\underline{t}_j = \otimes_{i=1}^3 (\underline{a}_{i\sigma_j(i)})$	$\bar{t}_j = \otimes_{i=1}^3 (\bar{a}_{i\sigma_j(i)})$
$\sigma_1 = 1, 2, 3$	$\underline{t}_1 = 2 \otimes -1 \otimes 1 = 2$	$\bar{t}_1 = 3 \otimes -1 \otimes 3 = 5$
$\sigma_2 = 1, 3, 2$	$\underline{t}_2 = 2 \otimes -1 \otimes 2 = 3$	$\bar{t}_2 = 3 \otimes 0 \otimes 3 = 6$
$\sigma_3 = 2, 1, 3$	$\underline{t}_3 = 2 \otimes 3 \otimes 1 = 6$	$\bar{t}_3 = 5 \otimes 5 \otimes 3 = 13$
$\sigma_4 = 2, 3, 1$	$\underline{t}_4 = 2 \otimes -1 \otimes -1 = 0$	$\bar{t}_4 = 5 \otimes 0 \otimes 2 = 7$
$\sigma_5 = 3, 1, 2$	$\underline{t}_5 = 0 \otimes 3 \otimes 2 = 5$	$\bar{t}_5 = 2 \otimes 5 \otimes 3 = 10$
$\sigma_6 = 3, 2, 1$	$\underline{t}_6 = 0 \otimes -2 \otimes -1 = -3$	$\bar{t}_6 = 2 \otimes -1 \otimes 2 = 3$

Then calculate the dominant value of the matrix  $\underline{A}$  using reference [24],

$$z^{\underline{A}} = \begin{pmatrix} z^2 & z^2 & z^0 \\ z^3 & z^{-2} & z^{-1} \\ z^{-1} & z^2 & z^1 \end{pmatrix},$$

because  $\det(z^{\underline{A}}) = z^1 - z^3 - z^6 + z^0 + z^5 - z^{-3} \neq 0$  results in  $\text{dom}(\underline{A}) = -3$ . Based on **Table 1**,  $\text{dom}(\underline{A}) = -3 = \underline{t}_6$ . Subsequently obtained  $\underline{S}_6, \underline{S}_{6e}, \underline{S}_{6o}, \underline{k}_{6e}$  and  $\underline{k}_{6o}$  which are written as

$$\begin{aligned}\underline{S}_6 &= \{\sigma \in P_3 \mid \underline{t}_3 = \otimes_{j=1}^3 (\underline{a}_{j\sigma(j)})\} = \{\sigma_6\}, \\ \underline{S}_{6e} &= \{\sigma \in \underline{S}_6 \mid \sigma \in P_3^e\} = \{\}, \\ \underline{S}_{6o} &= \{\sigma \in \underline{S}_6 \mid \sigma \in P_3^o\} = \{\sigma_6\}, \\ \underline{k}_{6e} &= |\underline{S}_{6e}| = 0, \text{ and } \underline{k}_{6o} = |\underline{S}_{6o}| = 1,\end{aligned}$$

with **Definition 2**, get  $\underline{k}_{6e} - \underline{k}_{6o} = 0 - 1 = -1 < 0$  so the value of  $\text{sign}(\underline{A}) = -1$ . Next, calculate the dominant matrix  $\bar{A}$  using reference [24] that is written as

$$z^{\bar{A}} = \begin{pmatrix} z^3 & z^5 & z^2 \\ z^5 & z^{-1} & z^0 \\ z^2 & z^3 & z^3 \end{pmatrix}$$

because  $\det(z^{\bar{A}}) = z^5 - z^6 - z^{13} + z^7 + z^{10} - z^3 \neq 0$  results in  $dom(\bar{A}) = 3$ . Based on **Table 1**,  $dom(\bar{A}) = 3 = \bar{t}_6$ . Subsequently obtained  $\bar{S}_6, \bar{S}_{6e}, \bar{S}_{6o}, \bar{k}_{6e}$  and  $\bar{k}_{6o}$  which are written as

$$\begin{aligned} \bar{S}_6 &= \{\sigma \in P_3 | \bar{t}_3 = \otimes_{j=1}^n (\bar{a}_{j\sigma(j)})\} = \{\sigma_6\}, \\ \bar{S}_{6e} &= \{\sigma \in \bar{S}_6 | \sigma \in P_3^e\} = \{\}, \\ \bar{S}_{6o} &= \{\sigma \in \bar{S}_6 | \sigma \in P_3^o\} = \{\sigma_6\}, \\ \bar{k}_{6e} &= |\bar{S}_{6e}| = 0, \text{ and } \bar{k}_{6o} = |\bar{S}_{6o}| = 1, \end{aligned}$$

with **Definition 2**, get  $\bar{k}_{6e} - \bar{k}_{6o} = 0 - 1 = -1 < 0$  so the value of  $sign(\bar{A}) = -1$ .

The following **Theorem 1** describes the sufficient condition of the system of linear equations  $A \otimes x = b$  with Cramer's rule in interval min-plus algebra.

**Theorem 1.** If  $sign(\underline{A}_i) = sign(\underline{A}), sign(\bar{A}_i) = sign(\bar{A})$  for  $1 \leq i \leq n$ , and  $dom(A) \approx [dom(\underline{A}), dom(\bar{A})] < [\varepsilon', \varepsilon']$  then  $x \approx [\underline{x}, \bar{x}]$  is a solution to the system of linear equations  $A \otimes x = b$  with  $x_i \otimes dom(A) = dom(A_i)$ .

**Proof.** Let  $A \otimes x = b$  with  $A \approx [\underline{A}, \bar{A}], x \approx [\underline{x}, \bar{x}]$ , and  $b \approx [\underline{b}, \bar{b}]$  be a system of linear equations. Assume  $sign(\underline{A}_i) = sign(\underline{A}), sign(\bar{A}_i) = sign(\bar{A})$  for  $1 \leq i \leq n$ , and  $dom(A) \approx [dom(\underline{A}), dom(\bar{A})] < [\varepsilon', \varepsilon']$ . Then, express the system in the form of  $z^A \approx [z^{\underline{A}}, z^{\bar{A}}], \xi \approx [\underline{\xi}, \bar{\xi}]$ , and  $z^b \approx [z^{\underline{b}}, z^{\bar{b}}]$ , we get the following equation.

$$z^A \xi = z^b \Leftrightarrow z^{\underline{A}} \underline{\xi} = z^{\underline{b}} \text{ and } z^{\bar{A}} \bar{\xi} = z^{\bar{b}} \tag{4}$$

Since  $dom(A) \approx [dom(\underline{A}), dom(\bar{A})] < [\varepsilon', \varepsilon']$  and  $\det(z^A) \neq [0,0]$ , **Equation (4)** can be solved using Cramer's rule. The solution of the interval matrix  $A$  with Cramer's rule is described as follows.

i. For  $\underline{A}$

$$\underline{\xi}_i = \frac{\det(z^{\underline{A}_i})}{\det(z^{\underline{A}})} \tag{5}$$

If  $z \rightarrow \infty$  then the value of  $\underline{\xi}_i$  is determined by the dominant of the right-hand segment in **Equation (5)**. The value of  $\det(z^{\underline{A}_i})$  will lead to the value of  $dom(\underline{A}_i)$  within the shape of  $z^{dom(\underline{A}_i)}$ , moreover for  $\det(z^{\underline{A}})$ . Suppose

$$\underline{d}_i = dom(\underline{A}_i), 1 \leq i \leq n \tag{6}$$

Based on the  $sign$  assumption,  $\underline{\xi}_i > 0$  is obtained so that  $\underline{\xi}_i$  can be written as

$$\underline{\xi}_i \approx z^{\underline{d}_i - dom(\underline{A})} \tag{7}$$

Furthermore, by substituting **Equation (7)** into  $z^{\underline{A}} \underline{\xi} = z^{\underline{b}}$ , we obtain

$$\sum_{j=1}^n z^{\underline{a}_{ij} + \underline{d}_j - dom(\underline{A})} \approx z^{\underline{b}_i} \tag{8}$$

**Equation (8)** in min-plus algebra has the meaning as

$$\bigotimes_{j=1}^n (\underline{a}_{ij} + \underline{d}_j - dom(\underline{A})) = \underline{b}_i, 1 \leq i \leq n \tag{9}$$

Thus, if  $\underline{x}_i = \underline{d}_i - dom(\underline{A}), 1 \leq i \leq n$  then  $\underline{x}_i$  is a solution to the system of linear equations  $\underline{A} \otimes \underline{x} = \underline{b}$ .

ii. For  $\bar{A}$

$$\bar{\xi}_i = \frac{\det(z^{\bar{A}_i})}{\det(z^{\bar{A}})} \quad (10)$$

If  $z \rightarrow \infty$  then the value of  $\bar{\xi}_i$  is determined by the dominant of the right-hand segment in equation (10). The value of  $\det(z^{\bar{A}_i})$  will lead to the value of  $\text{dom}(\bar{A}_i)$  within the shape of  $z^{\text{dom}(\bar{A}_i)}$ , moreover for  $\det(z^{\bar{A}})$ . Suppose

$$\bar{d}_i = \text{dom}(\bar{A}_i), 1 \leq i \leq n \quad (11)$$

Based on the *sign* assumption,  $\bar{\xi}_i > 0$  is obtained so that  $\bar{\xi}_i$  can be written as

$$\bar{\xi}_i \approx z^{\bar{d}_i - \text{dom}(\bar{A})} \quad (12)$$

Furthermore, by substituting **Equation (12)** into  $z^{\bar{A}}\bar{\xi} = z^{\bar{b}}$ , we obtain

$$\sum_{j=1}^n z^{\bar{a}_{ij} + \bar{d}_j - \text{dom}(\bar{A})} \approx z^{\bar{b}_i} \quad (13)$$

**Equation (13)** in min-plus algebra has the meaning as

$$\bigotimes_{j=1}^n (\bar{a}_{ij} + \bar{d}_j - \text{dom}(\bar{A})) = \bar{b}_i, 1 \leq i \leq n \quad (14)$$

Thus, if  $\bar{x}_i = \bar{d}_i - \text{dom}(\bar{A}), 1 \leq i \leq n$  then  $\bar{x}_i$  is a solution to the system of linear equations  $\bar{A} \bar{\otimes} \bar{x} = \bar{b}$ .

Thus, the obtained  $x \approx [\underline{x}, \bar{x}]$  is the solution of the system of linear equations  $A \bar{\otimes} x = b$  with  $x_i \bar{\otimes} \text{dom}(A) = \text{dom}(A_i)$ .

Here is the application of **Theorem 1** to solve the system of linear equations  $A \bar{\otimes} x = b$  in interval min-plus algebra

**Example 2.** Given a Linear Equation System  $A \bar{\otimes} x = b$  with  $A = \begin{pmatrix} [-3,1] & [-2,3] \\ [-1,5] & [-4,2] \end{pmatrix}$ ,  $x = \begin{pmatrix} [\underline{x}_1, \bar{x}_1] \\ [\underline{x}_2, \bar{x}_2] \end{pmatrix}$ , dan  $b = \begin{pmatrix} [-2,4] \\ [-2,4] \end{pmatrix}$ .

From the system of linear equations of interval min-plus algebra, a system of linear equations in min-plus algebra is obtained, namely

$$\begin{pmatrix} -3 & -2 \\ -1 & -4 \end{pmatrix} \bar{\otimes} \underline{x} = \begin{pmatrix} -2 \\ -2 \end{pmatrix} \quad (15)$$

And

$$\begin{pmatrix} 1 & 3 \\ 5 & 2 \end{pmatrix} \bar{\otimes} \bar{x} = \begin{pmatrix} 4 \\ 4 \end{pmatrix} \quad (16)$$

a. For the system of linear **Equation (15)**

$$\underline{A} = \begin{pmatrix} -3 & -2 \\ -1 & -4 \end{pmatrix} \text{ and } \underline{b} = \begin{pmatrix} -2 \\ -2 \end{pmatrix}$$

Checked whether the  $\text{sign}(\underline{A}) = \text{sign}(\underline{A}_i)$  value for  $i = 1, 2$  with  $a_j$  is the entries of the  $j$ -column of the matrix  $A$  and  $j = 1, 2$ .

$$z^{\underline{A}} = \begin{pmatrix} z^{-3} & z^{-2} \\ z^{-1} & z^{-4} \end{pmatrix},$$

obtained  $\det(z^{\underline{A}}) = z^{-7} - z^{-3}$ ,  $\text{dom}(\underline{A}) = -7$ ,  $\text{sign}(\underline{A}) = +1$ .

$$\underline{A}_1 = \begin{pmatrix} -2 & -2 \\ -2 & -4 \end{pmatrix}, z^{\underline{A}_1} = \begin{pmatrix} z^{-2} & z^{-2} \\ z^{-2} & z^{-4} \end{pmatrix},$$

obtained  $\det(z^{\underline{A}_1}) = z^{-6} - z^{-4}$ ,  $\text{dom}(\underline{A}_1) = -6$ ,  $\text{sign}(\underline{A}_1) = +1$ .

$$\underline{A}_2 = \begin{pmatrix} -3 & -2 \\ -1 & -2 \end{pmatrix}, z^{\underline{A}_2} = \begin{pmatrix} z^{-3} & z^{-2} \\ z^{-1} & z^{-2} \end{pmatrix},$$

obtained  $\det(z^{\underline{A}_2}) = z^{-5} - z^{-3}$ ,  $\text{dom}(\underline{A}_2) = -5$ ,  $\text{sign}(\underline{A}_2) = +1$ . Based on this calculation, the value of  $\text{sign}(\underline{A}) = \text{sign}(\underline{A}_1) = \text{sign}(\underline{A}_2)$  is shown. Referring to **Theorem 1**, the system of linear **Equation (15)** can be solved using Cramer's rule.

$$\underline{x}_1 \otimes \text{dom}(\underline{A}) = \text{dom}(\underline{A}_1)$$

$$\underline{x}_1 \otimes -7 = -6$$

$$\underline{x}_1 = 1$$

$$\underline{x}_2 \otimes \text{dom}(\underline{A}) = \text{dom}(\underline{A}_2)$$

$$\underline{x}_2 \otimes -7 = -5$$

$$\underline{x}_2 = 2$$

then obtained

$$\underline{x} = \begin{pmatrix} \underline{x}_1 \\ \underline{x}_2 \end{pmatrix} = \begin{pmatrix} 1 \\ 2 \end{pmatrix}, \quad (17)$$

with

$$\begin{pmatrix} -3 & -2 \\ -1 & -4 \end{pmatrix} \otimes \begin{pmatrix} 1 \\ 2 \end{pmatrix} = \begin{pmatrix} \min(-2,0) \\ \min(0,-2) \end{pmatrix} = \begin{pmatrix} -2 \\ -2 \end{pmatrix}.$$

Thus, the solution of the system of linear **Equation (15)** is **Equation (17)**.

b. for the system of linear **Equation (16)**

$$\bar{A} = \begin{pmatrix} 1 & 3 \\ 5 & 2 \end{pmatrix} \text{ and } \bar{b} = \begin{pmatrix} 4 \\ 4 \end{pmatrix}$$

Checked whether the  $\text{sign}(\bar{A}) = \text{sign}(\bar{A}_i)$  value for  $i = 1, 2$  with  $a_j$  is the entries of the  $j$ -column of the matrix  $A$  and  $j = 1, 2$ .

$$z^{\bar{A}} = \begin{pmatrix} z^1 & z^3 \\ z^5 & z^2 \end{pmatrix},$$

obtained  $\det(z^{\bar{A}}) = z^3 - z^8$ ,  $\text{dom}(\bar{A}) = 3$ ,  $\text{sign}(\bar{A}) = +1$ .

$$\bar{A}_1 = \begin{pmatrix} 4 & 3 \\ 4 & 2 \end{pmatrix}, z^{\bar{A}_1} = \begin{pmatrix} z^4 & z^3 \\ z^4 & z^2 \end{pmatrix},$$

obtained  $\det(z^{\bar{A}_1}) = z^6 - z^7$ ,  $\text{dom}(\bar{A}_1) = 6$ ,  $\text{sign}(\bar{A}_1) = +1$ .

$$\bar{A}_2 = \begin{pmatrix} 1 & 4 \\ 5 & 4 \end{pmatrix}, z^{\bar{A}_2} = \begin{pmatrix} z^1 & z^4 \\ z^5 & z^4 \end{pmatrix},$$

obtained  $\det(z^{\bar{A}_2}) = z^5 - z^9$ ,  $\text{dom}(\bar{A}_2) = 5$ ,  $\text{sign}(\bar{A}_2) = +1$ . Based on this calculation, the value of  $\text{sign}(\bar{A}) = \text{sign}(\bar{A}_1) = \text{sign}(\bar{A}_2)$  is shown. Referring to **Theorem 1**, the system of linear **Equation (16)** can be solved using Cramer's rule.

$$\bar{x}_1 \otimes \text{dom}(\bar{A}) = \text{dom}(\bar{A}_1)$$

$$\bar{x}_1 \otimes 3 = 6$$

$$\bar{x}_1 = 3$$

$$\bar{x}_2 \otimes \text{dom}(\bar{A}) = \text{dom}(\bar{A}_2)$$

$$\bar{x}_2 \otimes 3 = 5$$

$$\bar{x}_2 = 2$$

then obtained

$$\bar{x} = \begin{pmatrix} \bar{x}_1 \\ \bar{x}_2 \end{pmatrix} = \begin{pmatrix} 3 \\ 2 \end{pmatrix}, \quad (18)$$

with

$$\begin{pmatrix} 1 & 3 \\ 5 & 2 \end{pmatrix} \otimes \begin{pmatrix} 3 \\ 2 \end{pmatrix} = \begin{pmatrix} \min(4,5) \\ \min(8,4) \end{pmatrix} = \begin{pmatrix} 4 \\ 4 \end{pmatrix}.$$

Thus, the solution of the system of linear **Equation (16)** is **Equation (18)**.

Therefore, the solution of the system of linear equations  $\begin{pmatrix} [-3,1] & [-2,3] \\ [-1,5] & [-4,2] \end{pmatrix} \bar{\otimes} x = \begin{pmatrix} [-2,4] \\ [-2,4] \end{pmatrix}$  is  $x = \begin{pmatrix} [1,3] \\ [2,2] \end{pmatrix}$ .

#### 4. CONCLUSIONS

Based on the results and discussion, the sufficient conditions for a system of linear equations  $A \bar{\otimes} x = b$  in interval min-plus algebra to be solved using Cramer's rule are  $sign(\underline{A}_i) = sign(\underline{A}), sign(\bar{A}_i) = sign(\bar{A})$  for  $1 \leq i \leq n$ , and  $dom(A) \approx [dom(\underline{A}), dom(\bar{A})] < [\varepsilon', \varepsilon']$ . The Cramer rule is  $x_i \bar{\otimes} dom(A) = dom(A_i)$ . Readers who are interested in this topic can continue the research of Cramer's rule for matrix  $A \approx [\underline{A}, \bar{A}]$  with  $\underline{A}$  has inverse and  $\bar{A}$  has inverse.

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