

BAREKENG: Journal of Mathematics and Its ApplicationsJune 2023Volume 17 Issue 2Page 0615–0624P-ISSN: 1978-7227E-ISSN: 2615-3017

doi https://doi.org/10.30598/barekengvol17iss2pp0615-0624

DYNAMICAL SYSTEM FOR EBOLA OUTBREAK WITHIN QUARANTINE AND VACCINATION TREATMENTS

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ABSTRACT

Article History:

Received: 23rd August 2022 Revised: 5th April 2023 Accepted: 7th April 2023

Keywords:

Dynamical system; Ebola virus disease; Equilibrium point; Stability analysis.



Ebola Virus Disease (EVD) is an infectious disease with a high mortality rate caused by the virus from the family of Filoviridae, the genus of Ebolavirus. Therefore, this research works on the developing model of Ebola disease spread with SLSHVEQIHR type. The purpose of this study is to analyze the spread of Ebola disease with the treatments, which are quarantine and vaccination. Then determine the equilibrium point and basic reproduction number (R_0). There are two equilibrium points, the disease-free equilibrium point and the endemic equilibrium point. The analysis results in the model show that if $R_0 < 1$ then the disease free equilibrium point is locally asymptotically stable. If $R_0 > 1$ then the endemic equilibrium point is locally asymptotically stable. Numerical simulations are performed to show the population dynamics when $R_0 < 1$ and $R_0 > 1$.

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How to cite this article:

S. Nurwijaya, R. K. MA and S. Sugiarto., "DYNAMICAL SYSTEM FOR EBOLA OUTBREAK WITHIN QUARANTINE AND VACCINATION TREATMENTS," *BAREKENG: J. Math. & App.*, vol. 17, iss. 2, pp. 0615-0624, June, 2023.

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1. INTRODUCTION

Ebola Virus Disease (EVD) is a viral infection caused by a virus from the family *Filoviridae*, the genus *Ebolavirus*, that derived from fruit bats, the family *Pteropodidae* [1]. EVD is a deadly infectious disease that was first discovered in the Democratic Republic of Congo (DRC) near the Ebola River in 1976 [2][3]. The last case of EVD reappeared in 2014 on March 23, with deaths reaching 11,315 out of 28,637 cases occurring in 6 countries until January 2016 [4]. EVD is spread through direct contact with infected body fluids in the mouth, nose, eyes or through a break in the skin [5][6]. The virus is not transmitted through the air, by water, or in general, by food [6].

Individuals suffering from EVD do not infect others during the incubation period, which can survive between two days and three weeks. The recovery from EVD relies heavily on the immune response of infected individuals and support for good clinical care. Individuals who have recovered cannot spread the ebola virus. However, Ebola virus can stay in body fluids such as semen and breast milk for some time after recovery [6][7].

For years, researchers have been trying to develop a model for the spread of EVD since Ebola's disease became a deadly infectious disease. The mathematical model of EVD spread aims to analyze the characteristics of the spread of the disease [8][9]. Imran et al. [10] developed a model of the spread of ebola disease with S_LS_HEIHR type by providing treatment in the hospital for infected individuals. The treatment aims to provide recovery to an infected individual or reduce the rate of death caused by EVD.

According to WHO in 2021 [7], the recombinant Vesicular Virus-Ebola Virus Virus vaccine (rVSV– ZEBOV) is effective in reducing the risk of infected populations. So Wintachai and Prathom [11] use the SEIR model equipped with the effectiveness of vaccination to forecast the COVID-19 situation when a vaccine comes out and Muhammad et al. [12] modified the S_LS_HEIHR type of disease model to S_LS_HVEIHR type by adding treatment in the form of vaccine against susceptible individuals to reduce the risk of infection and the S_LS_HEQIHR by adding quarantine treatment to prevent transmission of the disease from infected individuals.

2. RESEARCH METHODS

This research modified the S_LS_HEIHR type of disease model to $S_LS_HVEQIHR$ type by adding treatment in the form of vaccine against susceptible individuals to reduce the risk of infection and adding quarantine treatment to prevent transmission of the disease from infected individuals. The total population at any time instant t, denoted by N(t), is the sum of individual populations in each compartment that includes low risk susceptible individuals $S_L(t)$, high risk susceptible individuals $S_H(t)$, vaccinated individuals V(t), exposed individuals E(t), quarantined individuals Q(t), and infected individuals I(t), Hospitalized individuals H(t), and Recovered individuals R(t), such that, $N(t) = S_L(t) + S_H(t) + V(t) + E(t) + Q(t) + I(t) + H(t) + R(t)$. The flow diagram of Ebola model is shown in Figure 1.

Based on the diagram in Figure 1, we can obtain a system of ordinary differential equations as follows:

$$\frac{dS_L}{dt} = \Pi(1-p) - \lambda S_L - \gamma_L S_L - \mu S_L$$

$$\frac{dS_H}{dt} = \Pi p - \lambda \psi_H S_H - \gamma_H S_H - \mu S_H$$

$$\frac{dV}{dt} = \gamma_L S_L + \gamma_H S_H - \lambda (1-\varepsilon)V - \mu V$$

$$\frac{dE}{dt} = \lambda S_L + \lambda \psi_H S_H + \lambda (1-\varepsilon)V - (\xi + \alpha + \mu)E$$
(1)
$$\frac{dQ}{dt} = \xi E - \tau_Q Q - \mu Q$$

$$\frac{dI}{dt} = \alpha E - (\theta_I + \tau + \delta_I + \mu)I$$

$$\frac{dH}{dt} = \tau_Q Q + \tau I - (\theta_H + \delta_H + \mu)H$$

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$$\frac{dR}{dt} = \theta_H H + \theta_I I - \mu R$$

where $\lambda = \frac{\beta(I+\eta H)}{N}$.

According to system of Equation (1) we have

$$\frac{dN}{dt} = \Pi - \mu N - \theta_H H - \theta_I I.$$

All parameters are non-negative constants.



Figure 1. Diagram depicting the dynamics of the Ebola virus

3. RESULTS AND DISCUSSION

In this section, we will determine the equilibrium point, the basic reproduction number, and the stability analysis.

3.1. The Equilibrium Point

The disease-free equilibrium of the system of Equation (1) is given by

$$T^{0}(S_{L}, S_{H}, V, E, Q, I, H, R) = (S_{L}^{0}, S_{H}^{0}, V^{0}, 0, 0, 0, 0, 0),$$

where

$$S_{L}^{0} = \frac{\Pi(1-p)}{\gamma_{L}+\mu}, \ S_{H}^{0} = \frac{\Pi p}{\gamma_{H}+\mu}, \ V^{0} = \left(\frac{\Pi(1-p)\gamma_{L}}{\mu(\gamma_{L}+\mu)} + \frac{\Pi p\gamma_{H}}{\mu(\gamma_{H}+\mu)}\right)$$

and the endemic equilibrium of the system (1) is given by

$$T^{*}(S_{L}, S_{H}, V, E, Q, I, H, R) = (S_{L}^{*}, S_{H}^{*}, V^{*}, E^{*}, Q^{*}, I^{*}, H^{*}, R^{*})$$

where

3.2. The Basic Reproduction Number

The basic reproduction number, denoted (R_0) is the expected number of secondary cases produced, in a completely susceptible population, by a typical infective individual. We calculate the basic reproduction number by using the next generation operator approach by van den Driessche and Watmough [13][14]. The next generation matrix at the disease-free equilibrium T^0 is given by:

where

$$\Omega = \left(\frac{(1-p)\mu}{\gamma_L + \mu} + \frac{\psi_H p\mu}{\gamma_H + \mu} + \left(1 - \varepsilon\right) \left(\frac{(1-p)\gamma_L}{\gamma_L + \mu} + \frac{p\gamma_H}{\gamma_H + \mu}\right)\right)$$

and

$$V = \begin{pmatrix} k_1 & 0 & 0 & 0 \\ -\xi & k_2 & 0 & 0 \\ -\alpha & 0 & k_3 & 0 \\ 0 & -\tau_Q & -\tau & k_4 \end{pmatrix}$$

where

The basic reproduction number R_0 is dominant eigenvalue of $G = FV^{-1}$, thus we get

$$R_{0} = \beta \Omega \Big(\frac{\alpha k_{2} k_{4} + \alpha \eta \, k_{2} + \eta \xi \tau_{Q} k_{3}}{k_{1} k_{2} k_{3} k_{4}} \Big) = R_{0}^{1} + R_{0}^{2} + R_{0}^{3} \,,$$

where

$$R_0^1 = \beta \Omega\left(\frac{\alpha k_2 k_4}{k_1 k_2 k_3 k_4}\right), R_0^2 = \beta \Omega\left(\frac{\alpha \eta \pi k_2}{k_1 k_2 k_3 k_4}\right), \text{ and } R_0^3 = \beta \Omega\left(\frac{\eta \xi \tau_Q k_3}{k_1 k_2 k_3 k_4}\right)$$

3.3. The Stability Analysis

The stability of system of Equation (1) is dependent on the basic reproduction number R_0 . The stability analysis of both equilibrium T^0 and T^* will be provided through the following theorems:

Theorem 1. The disease-free equilibrium T^0 for system of Equation (1) is locally asymptotically stable if $R_0 < 1$.

Proof. The Jacobian matrix at T^0 for system of Equation (1) is given by

$$J_{T^0} = \begin{pmatrix} J_{11} & 0 & 0 & 0 & 0 & J_{16} & J_{17} & 0 \\ 0 & J_{22} & 0 & 0 & 0 & J_{26} & J_{27} & 0 \\ J_{31} & J_{32} & J_{33} & 0 & 0 & J_{36} & J_{37} & 0 \\ 0 & 0 & 0 & J_{44} & 0 & J_{46} & J_{47} & 0 \\ 0 & 0 & 0 & J_{54} & J_{55} & 0 & 0 & 0 \\ 0 & 0 & 0 & J_{64} & 0 & J_{66} & 0 & 0 \\ 0 & 0 & 0 & 0 & J_{75} & J_{76} & J_{77} & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & J_{86} & J_{87} & J_{88} \end{pmatrix}$$

$$\begin{split} J_{11} &= -\left(\gamma_{L} + \mu\right), & J_{46} = \beta\Omega, \\ J_{16} &= -\frac{\beta}{N} S_{L}^{0}, & J_{47} = \beta \eta\Omega, \\ J_{17} &= -\frac{\beta\eta}{N} S_{L}^{0}, & J_{54} = \xi, \\ J_{22} &= -\left(\gamma_{H} + \mu\right), & J_{55} = -k_{2}, \\ J_{26} &= -\frac{\beta}{N} \psi_{H} S_{H}^{0}, & J_{64} = \alpha, \\ J_{27} &= -\frac{\beta\eta}{N} \psi_{H} S_{H}^{0}, & J_{66} = -k_{3}, \\ J_{31} &= \gamma_{L}, & J_{75} = \tau_{Q}, \\ J_{32} &= \gamma_{H}, & J_{76} = \tau, \\ J_{33} &= -\mu, & J_{76} = \tau, \\ J_{36} &= -\frac{\beta}{N} (1 - \varepsilon) V^{0}, & J_{86} = \theta_{I}, \\ J_{37} &= -\frac{\beta\eta}{N} (1 - \varepsilon) V^{0}, & J_{87} = \theta_{H}, \\ J_{44} &= -k_{1}, & J_{88} = -\mu. \end{split}$$

The eigenvalue was determined for the disease-free equibrium T^0 by using the equation $|J_{T^0} - \lambda I| = 0$, so we get the characteristic equation as follow:

$$(J_{11} - \lambda)(J_{22} - \lambda)(J_{33} - \lambda)(J_{88} - \lambda)(\lambda^4 + a_1\lambda^3 + a_2\lambda^2 + a_3\lambda + a_4) = 0$$
(2)

where

$$\begin{aligned} a_1 &= k_1 + k_2 + k_3 + k_4, \\ a_2 &= k_1 k_2 + k_2 k_3 + k_1 k_4 + k_2 k_4 + k_3 k_4 + (1 - R_0^1) k_1 k_3, \\ a_3 &= k_1 k_2 k_3 (1 - R_0^1) + k_1 k_3 k_4 (1 - R_0^2) + k_1 k_2 k_4 (1 - R_0^3) + k_2 k_3 k_4 (1 - R_0^1), \\ a_4 &= k_1 k_2 k_3 k_4 (1 - R_0). \end{aligned}$$

According to Equation (2), we obtain eight eigenvalues with four of them are negative:

$$\begin{split} \lambda_1 &= J_{11} = -(\gamma_L + \mu), \\ \lambda_2 &= J_{22} = -(\gamma_H + \mu), \end{split} \qquad \qquad \lambda_3 &= J_{33} = -\mu, \\ \lambda_4 &= J_{88} = -\mu. \end{split}$$

Whereas the others are getting by solving the equation below:

$$(\lambda^4 + a_1\lambda^3 + a_2\lambda^2 + a_3\lambda + a_4) = 0 \tag{3}$$

According to Routh-Hurwitz criterion [15][16], Equation (3) on disease-free equilibrium T^0 is stable if the following stability criterion satisfied:

$$a_1 > 0, a_2 > 0, a_3 > 0, a_4 > 0, a_1 a_2 > a_3, \text{ and } a_1 a_2 a_3 > (a_3^2 + a_1^2 a_4)$$
 (4)

Based on Equation (4), since all parameters k_1 , k_2 , k_3 , and k_4 are positive, then a_1 is positive. Furthermore, $R_0 < 1$ then the coefficient a_4 will be positive. Further, for coefficient a_2 and a_3 will be positive if $R_0^1 < 1$ and $R_0^2 < 1$ and $R_0^3 < 1$. Since $R_0 < 1$, then $R_0^1 < 1$, $R_0^2 < 1$, and $R_0^3 < 1$. Afterward to proof $a_1a_2 > a_3$ and $a_1a_2a_3 > (a_3^2 + a_1^2a_4)$, we need the parameter value at condition $R_0 < 1$. So for $R_0 < 1$ the (4) condition is satisfied. Thus, proved that disease-free equilibrium T^0 for system of Equation (1) is locally asymptotically stable if $R_0 < 1$. **Theorem 2.** If $R_0 > 1$ then the endemic equilibrium T^* is locally asymptotically stable.

Proof. According to Castillo-Chaves and Song [17], let $\varphi = \beta$ be the bifurcation parameter. According to condition $R_0 = 1$ we have

$$\varphi = \varphi^* = \frac{k_1 k_2 k_3 k_4}{\Omega(\alpha k_2 k_4 + \alpha \eta \pi k_2 + \eta \xi \tau_Q k_3)}$$

Disease-free equilibrium T^0 has one zero eigenvalue and seven negative eigenvalues if $R_0 = 1$ or $\varphi = \varphi^*$. The zero eigenvalue has right eigenvector $(u_1, u_2, u_3, u_4, u_5, u_6, u_7, u_8)$ and left eigenvector $(v_1, v_2, v_3, v_4, v_5, v_6, v_7, v_8)$. As indicated previously that u_4 is arbitrary positive, then

$$\begin{split} u_{5} &= \frac{\xi}{k_{2}} \, u_{4} > 0, \\ u_{6} &= \frac{\alpha}{k_{3}} \, u_{4} > 0, \\ u_{7} &= \left(\frac{\xi \tau_{0}}{k_{2}k_{4}} + \frac{\alpha \tau}{k_{3}k_{4}}\right) u_{4} > 0, \\ u_{8} &= \left(\frac{\alpha \theta_{I}}{\mu k_{3}} + \frac{\xi \theta_{H} \tau_{0}}{\mu k_{2}k_{4}} + \frac{\alpha \theta_{H} \tau}{\mu k_{3}k_{4}}\right) u_{4} > 0, \\ u_{1} &= -\left(\frac{\alpha \beta \Pi(1-p)}{N(\gamma_{L}+\mu)^{2}k_{3}} + \frac{\beta \eta \Pi(1-p)}{N(\gamma_{L}+\mu)^{2}} \left(\frac{\xi \tau_{0}}{k_{2}k_{4}} + \frac{\alpha \tau}{k_{3}k_{4}}\right)\right) u_{4} < 0, \\ u_{2} &= -\left(\frac{\alpha \beta \psi_{H} \Pi p}{N(\gamma_{H}+\mu)^{2}k_{3}} + \frac{\beta \eta \psi_{H} \Pi p}{N(\gamma_{L}+\mu)^{2}} \left(\frac{\xi \tau_{0}}{k_{2}k_{4}} + \frac{\alpha \tau}{k_{3}k_{4}}\right)\right) u_{4} < 0, \\ u_{3} &= -\left(\left(\frac{\alpha \beta \Pi(1-p)}{N(\gamma_{L}+\mu)^{2}k_{3}} + \frac{\beta \eta \Pi(1-p)}{N(\gamma_{L}+\mu)^{2}} \left(\frac{\xi \tau_{0}}{k_{2}k_{4}} + \frac{\alpha \tau}{k_{3}k_{4}}\right)\right) + \left(\frac{\alpha \beta \psi_{H} \Pi p}{N(\gamma_{H}+\mu)^{2}k_{3}} + \frac{\beta \eta \psi_{H} \Pi p}{N(\gamma_{L}+\mu)^{2}} \left(\frac{\xi \tau_{0}}{k_{2}k_{4}} + \frac{\alpha \tau}{k_{3}k_{4}}\right)\right) + \left(\alpha \beta (1-\varepsilon) \left(\frac{\Pi(1-p)\gamma_{L}}{N(\gamma_{L}+\mu)\mu^{2}k_{3}} + \frac{\Pi p \gamma_{H}}{N(\gamma_{H}+\mu)\mu^{2}k_{3}}\right)\right) + \left(\beta \eta (1-\varepsilon) \left(\frac{\Pi(1-p)\gamma_{L}}{N(\gamma_{L}+\mu)\mu^{2}} + \frac{\Pi p \gamma_{H}}{N(\gamma_{H}+\mu)\mu^{2}}\right) \left(\frac{\xi \tau_{0}}{k_{2}k_{4}} + \frac{\alpha \tau}{k_{3}k_{4}}\right) \right) u_{4} < 0. \end{split}$$

As indicated previously that v_5 is arbitrary positive, then, $v_1 = v_2 = v_3 = v_8 = 0$,

$$v_7 = \frac{k_2}{\tau_Q} v_5 > 0, v_4 = \left(\frac{Nk_2k_4}{\beta\eta\Omega\tau_Q}\right) v_5 > 0, v_6 = \left(\frac{k_2k_4}{\eta\tau_Qk_3} + \frac{\tau k_2}{\tau_Qk_3}\right) v_5 > 0.$$

Define

$$a = \sum_{k,i,j=1}^{8} v_k u_i u_j \frac{\partial^2 f_k}{\partial x_i \partial x_j} (T^0, \varphi^*), \quad b = \sum_{k,i,j=1}^{8} v_k u_i \frac{\partial^2 f_k}{\partial x_i \partial \varphi} (T^0, \varphi^*).$$

$$(5)$$

where

$$x_1 = S_L \qquad x_2 = S_H \qquad x_3 = V \qquad x_4 = E$$

$$x_5 = Q \qquad x_6 = I \qquad x_7 = H \qquad x_6 = R$$

$$f_{1} = \frac{dx_{1}}{dt} = \prod(1-p) - \frac{\varphi(x_{6}+\eta x_{7})}{N} x_{1} - \gamma_{L} x_{1} - \mu x_{1},$$

$$f_{2} = \frac{dx_{2}}{dt} = \prod p - \frac{\varphi(x_{6}+\eta x_{7})}{N} \psi_{H} x_{2} - \gamma_{H} x_{2} - \mu x_{2},$$

$$f_{3} = \frac{dx_{3}}{dt} = \gamma_{L} x_{1} + \gamma_{H} x_{2} - \frac{\varphi(x_{6}+\eta x_{7})}{N} (1-\varepsilon) x_{3} - \mu x_{3},$$

$$f_{4} = \frac{dx_{4}}{dt} = \frac{\varphi(x_{6}+\eta x_{7})}{N} (x_{1} + \psi_{H} x_{2} + (1-\varepsilon) x_{3}) - (\xi + \alpha + \mu) x_{4},$$

$$f_{5} = \frac{dx_{5}}{dt} = \xi x_{4} - \tau_{Q} x_{5} - \mu x_{5},$$

$$f_{6} = \frac{dx_{6}}{dt} = \alpha x_{4} - (\theta_{I} + \tau + \delta_{I} + \mu) x_{6},$$

$$f_{7} = \frac{dx_{7}}{dt} = \tau_{Q} x_{5} + \tau x_{6} - (\theta_{H} + \delta_{H} + \mu) x_{7},$$

$$f_{8} = \frac{dx_{8}}{dt} = \theta_{I} x_{6} + \theta_{H} x_{7} - \mu x_{8}.$$

According to Equation (5), we obtain

$$a = v_4 \left(u_1 u_6 \frac{\varphi^*}{N} + u_1 u_7 \frac{\eta \varphi^*}{N} + u_2 u_6 \frac{\psi_H \varphi^*}{N} + u_2 u_7 \frac{\psi_H \eta \varphi^*}{N} + u_3 u_6 \frac{(1-\varepsilon)\varphi^*}{N} + u_3 u_7 \frac{(1-\varepsilon)\eta \varphi^*}{N} \right) \text{ and } b = v_4 u_6 \Omega + v_4 u_7 \eta \Omega.$$

Since v_4 , u_6 , $u_7 > 0$ and u_1 , u_2 , $u_3 < 0$, then a < 0 and b > 0.

Consequently, when φ changes from $\varphi < \varphi^*(R_0 < 1)$ to $\varphi > \varphi^*(R_0 > 1)$, the disease-free equilibrium T^0 stability changes from stable and becomes unstable, while endemic equilibrium T^* coordinates changes from negative becomes positive and thus becomes local asymptotically stable. As a consequence, the endemic equilibrium T^* is locally asymptotically stable if $R_0 > 1$.

3.4. Numerical Simulations

The numerical simulations were performed to visualize stability properties of the equilibrium points of both T^0 and T^* based on the **Theorem 1** and **Theorem 2**. The initial values used are $S_L(0) = 25$, $S_H(0) = 25$, V(0) = 10, E(0) = 10, Q(0) = 10, I(0) = 5, H(0) = 5, and R(0) = 10. The parameter values used in this simulation are shown in **Table 1**. For the disease free equilibrium we have $R_0 = 0.17786 < 1$ and the disease free equilibrium $T^0(1.571, 0.371, 104.976, 0, 0, 0, 0, 0)$. The population dynamics at condition $R_0 < 1$ is shown in **Figure 2**. For the endemic equilibrium we have $R_0 = 1.93725 > 1$ and the endemic equilibrium $T^*(S_L = 4.078, S_H = 1.145, V = 15.580, E = 15.580, E = 1.418, Q = 1.392, I = 0.150, H = 1.555, R = 20.507$). The population dynamics at condition $R_0 > 1$ is shown in **Figure 3**.

Figure 2 supports Theorem 1 and Figure 3 supports Theorem 2. This simulation shows that the system will be stable at around disease-free equilibrium when $R_0 < 1$ and the system will be stable at around endemic equilibrium when $R_0 > 1$.



(a) Low risk and high risk susceptible population, (b) Vaccinated population, (c) Exposed and quarantined population, (d) Infected and hospitalized population, (e) Recovered population

Table 1. Parameter values		
Parameter	R ₀ < 1	$R_0 > 1$
	Value	Value
П	1.70 in[10]	1.70 in [10]
p	0.20in [10]	0.20in [10]
ψ_{H}	1.20in [10]	1.20in [10]
β	0.39 in [10]	0.39 in [10]
η	1.50 in [10]	1.50 in [10]
α	0.10in [10]	0.10in [10]
τ	0.16in [10]	0.16in [10]
$ heta_I$	0.10in [10]	0.10in [10]
$ heta_{H}$	0.20in [10]	0.20in [10]
δ_I	0.67 in [17]	0.67 in[17]
δ_H	0.58 in [17]	0.58 in[17]
μ	0.0159 in [10]	0.0159 in [10]
γ_L	0.65 [assumed]	0.25 [assumed]
γ_{H}	0.60[assumed]	0.20[assumed]
ε	0.75[assumed]	0.25 [assumed]
ξ	0.35 [assumed]	0.85 [assumed]
τ_0	0.40 [assumed]	0.85 [assumed]





4. CONCLUSION

This study modified mathematical model of Ebola outbreak to consider quarantine and vaccination. The results of the model analysis obtained two equilibrium points, namely, disease-free equilibrium and endemic equilibrium. The basic reproduction number (R_0) was determined. The disease-free equilibrium is locally asymptotically stable on condition $R_0 < 1$, whereas the endemic equilibrium is locally asymptotically stable on condition $R_0 > 1$. The numerical simulation of population dynamics showed similar patterns as expected.

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